

# LT87 Series Multi Axis Joystick

## Product Features

- Ergonomic design, mainly for high altitude working vehicle design application.
- The non-contact Hall sensor detects the operating angle.
- The spring return handle can be operated in any direction of single or double shaft.
- The type of the upper end and the number of switches and whether to configure analog quantity can be customized.
- Optional CAN bus output.

## Application

This series of products are mainly used in high-altitude working arm truck, road machinery, fire fighting vehicles, mining machinery and other equipment.

## Technical Information

### Electrical data

Hall	
Supply voltage	5±0.5Vdc
Supply current	<11 mA (Each hall sensor)
Limit allowed overvoltage	20Vdc
Reverse limit allowable voltage	-10Vdc
Linear error of output voltage	±0.2Vdc
CAN BUS	
Mains input	9~36Vdc
CAN	CAN2.0B
Agreement	J1939
Connection port	Customization

### Mechanical parameter

Shaking angle	±23°before and after ±18°
Operating mode	Automatic spring reset
Starting force	4N
Maximum operating force	11N
Margin pressure test location	>300N
Service life	>2M
Weight	About 1KG

### Environmental parameter

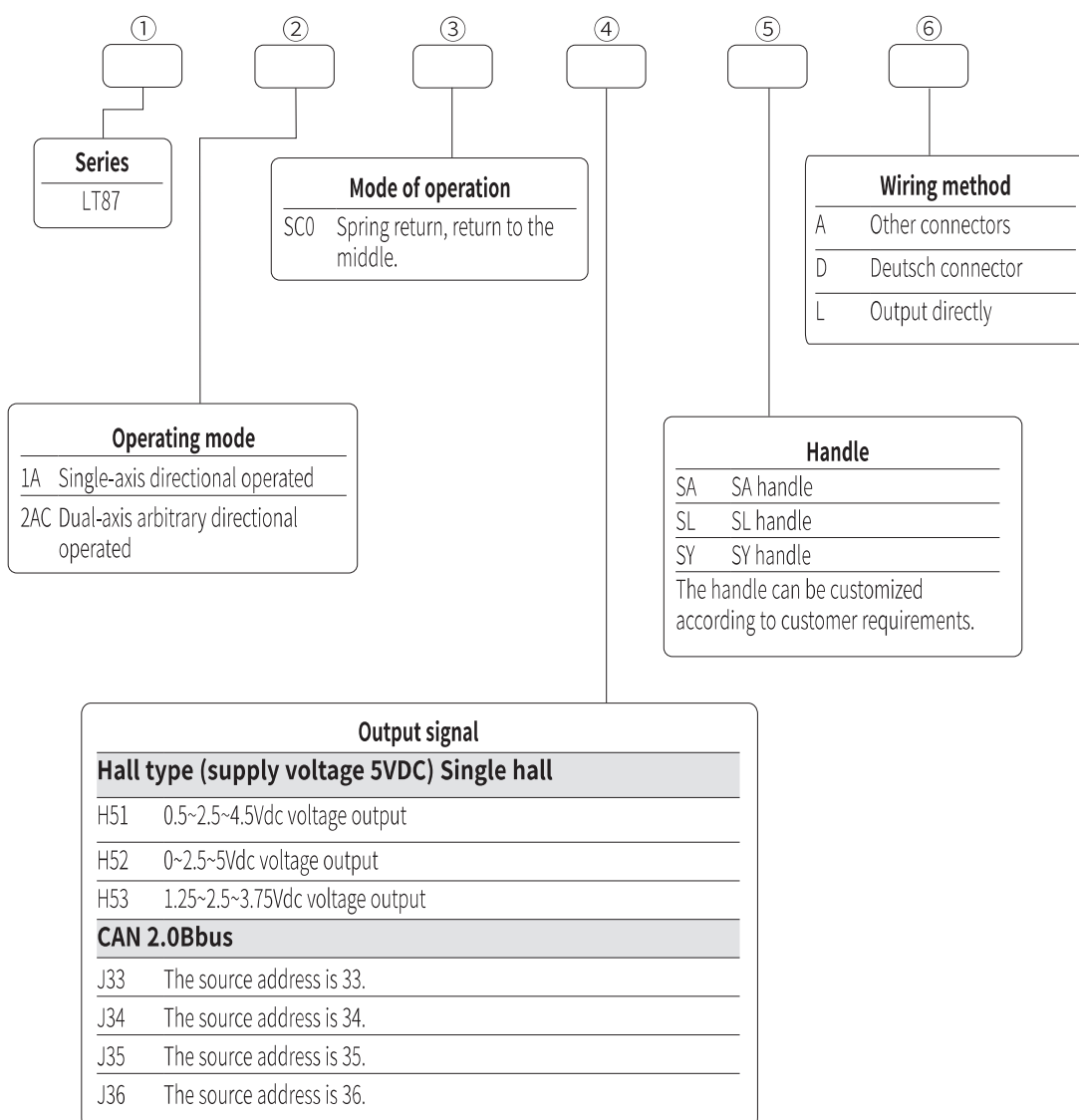
Operating temperature	-30C~+70°C
Storage temperature	-40°C~+85°C
Level of protection	IP65 (Above mounting panel)



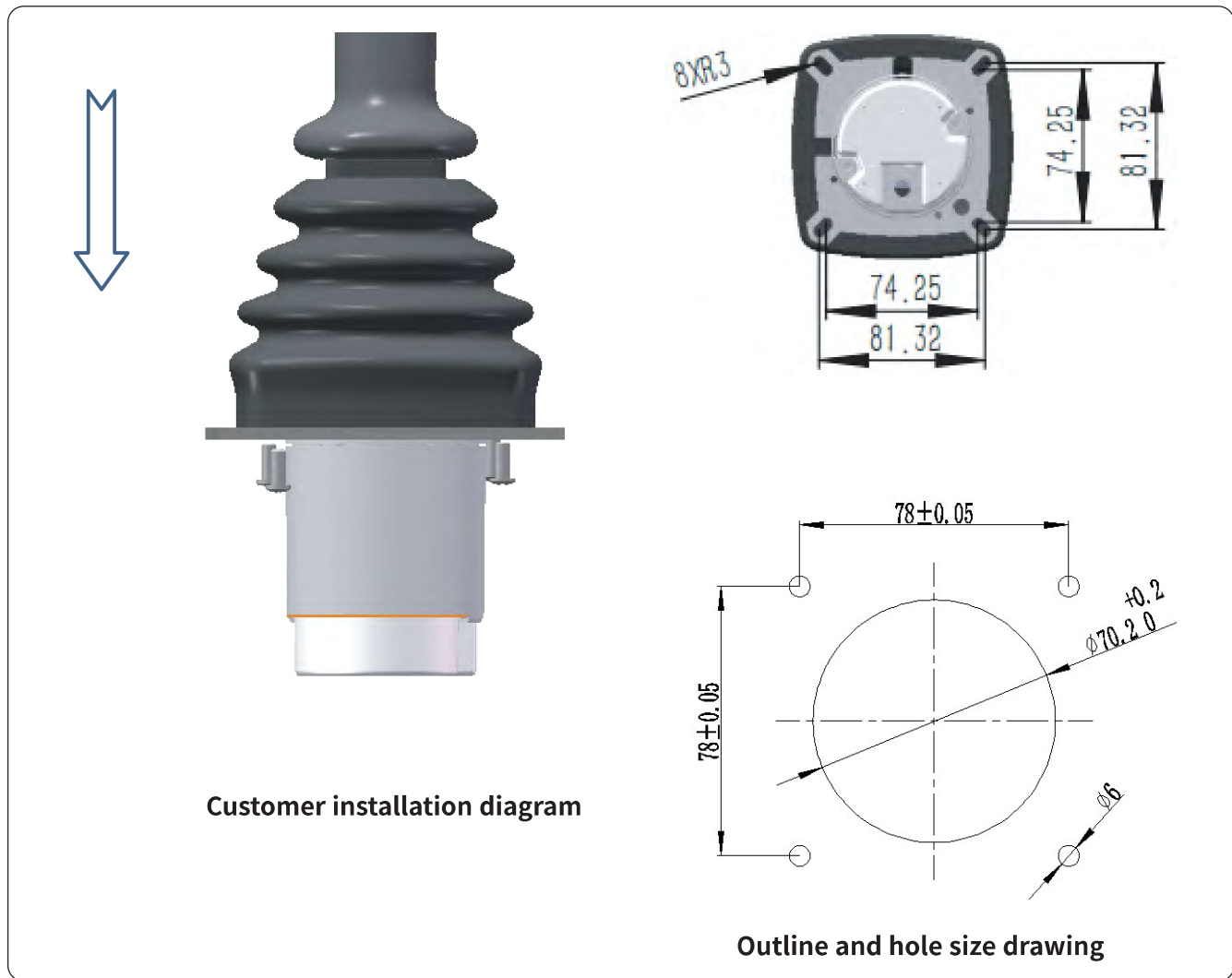
## Dimensions



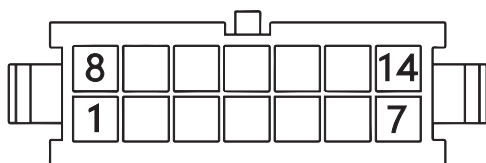
## Product Configuration



## Product Installation



## Qualification definition



**Wiring diagram**

The bottom line definition			Top out line definition	
Pin	Line color	Function	Line color	Function
1	Red	The supply voltage is 5Vdc	White	Stilt Plate left (1a)
2-3			Red	Common end of stilt board (1)
4	Black	Power supply 0V	Brown	Stilt Plate right (1a)
5	Blue	The supply voltage is 12Vdc.		
6-8				
9	Green	Hall output.		
10				
11	Gray	Y-output 12V (rear direction)		
12				
13	Brown	Y+ Output 12V (rear direction)		
14				